



Towed Hydrographic Survey Platform for Compact MBES Deployment

UTS San Diego 2015

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CIDCO



The Interdisciplinary Centre for the Development of Ocean Mapping (CIDCO) is a not for profit organization in marine geomatics based in Rimouski (Qc), Canada.

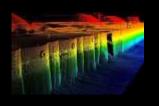


Source: GEBCO world map

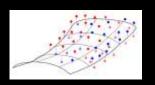


CIDCO's main active projects





Infrastructure inspection expertise centre



Automatic calibration (boresight and latency) method



SBES and MBES bathymetric surveys in non-traditional environments



Self-reliant QC algorithms for USV platforms



Course in Hydrographic Surveying category B programme



THIS is a Towed Hydrographic Survey Platform









The challenge



Boat

MBES / SBES IMU & GPS SV probe











What people do



Boat

MBES / SBES IMU & GPS SV probe Imagination
Pipes / flanges
Straps
Tools

. . .



















Teledyne Reson - HydroBat Composite







Teledyne Reson – SeaBat 7125









Teledyne Reson – SeaBat 7125 SV2









Teledyne Reson – SeaBat T20-P



Conclusion



The universal sonar mount does not exist!



Paradigm shift



MBES / SBES IMU & GPS SV probe Towed Hydrographic Survey Platform Boat









HydroBall™



A robust spherical shell casing (7kg – 40cm diam) encloses:

- A single beam echosounder

- A L1/L2 GPS receiver

- A digital compass (heading,

pitch, roll)





HydroBall™













Waterproof caisson

Sonar & IMU mounting plate

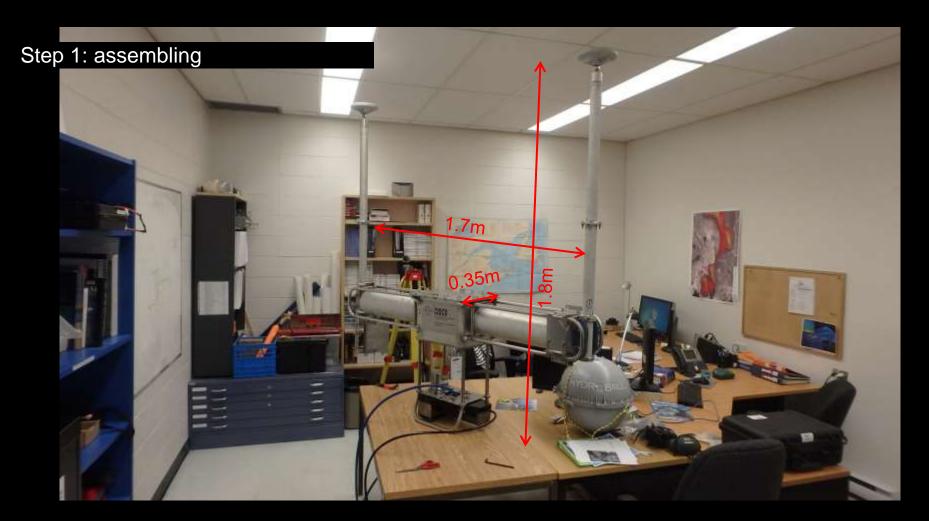
GNSS antennas' masts

Floats

All can be carried into 2 cases

























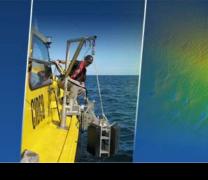


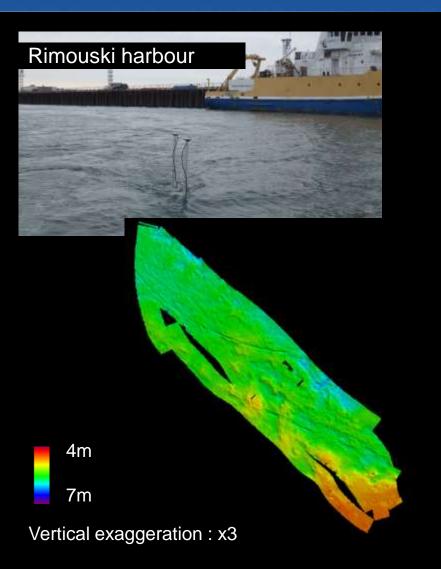




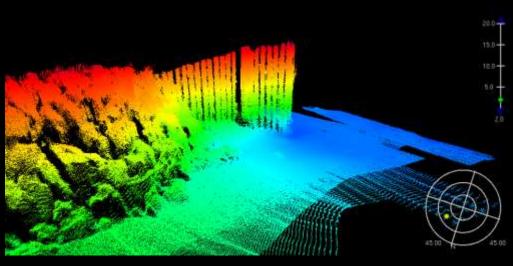


3 short surveys











Data processing



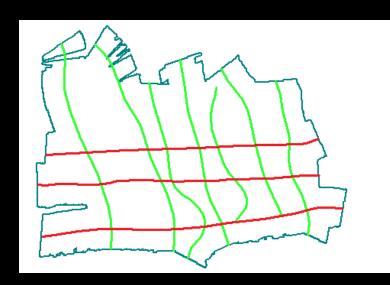
HIPS processing workflow:

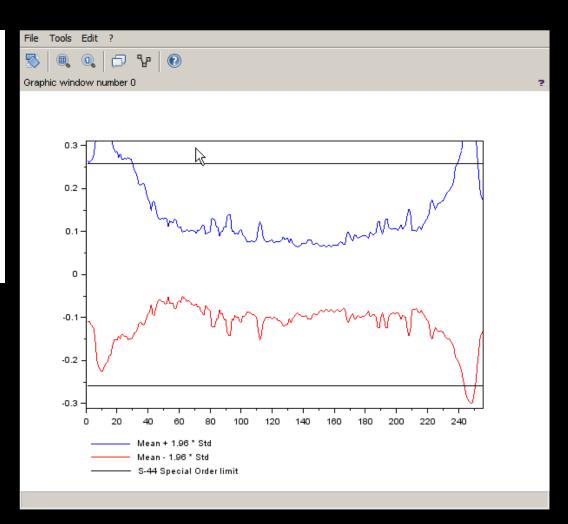
- VesselFile definition
- Sound velocity correction
- Water level correction
- Soundings editing
- Merge
- Base surface creation



QC / vertical precision





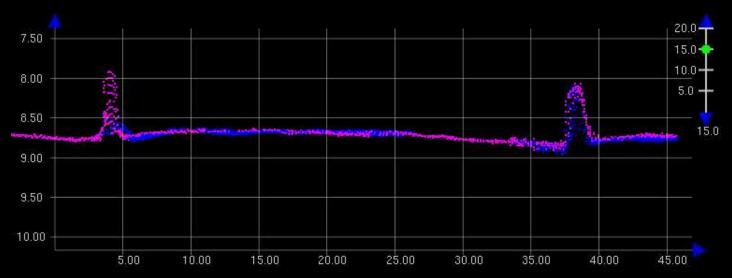




QC / horizontal precision



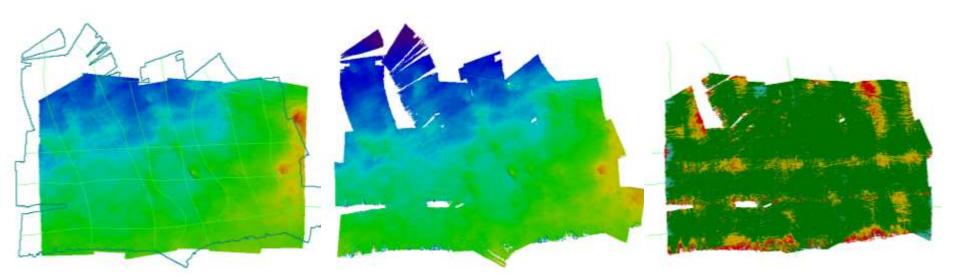






QC / survey accuracy





Ref surface: 7125SV2 boat mounted

Eval surface: T20-P towed

Diff surface



QC / survey accuracy





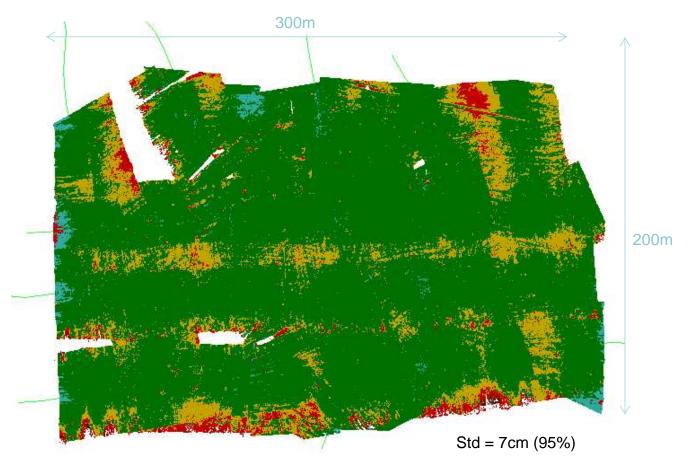
+0.10m

+0.05m

-0.05m

-0.10m

-0.25m





Conclusion







Conclusion







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